Logical Characterizations in **Distributed** Computing Jukka Suomela

Aalto University

Recently in Paris...

I was one of the examiners in Fabian Reiter's PhD defense at Paris Diderot

Fabian's talk started with *Fagin's theorem* and then proceeded to introduce the *"Helsinki–Tampere theorem"*

What is this about?

Back to February 2010

I gave a talk in the Finite Model Theory Seminar on an unusual topic: models of distributed computing

Led to a collaboration that initiated the study of *distributed graph algorithms* from the perspective of *descriptive complexity*

Helsinki–Tampere team

- Lauri Hella Tuomo Lempiäinen
- Matti Järvisalo Kerkko Luosto
- Antti Kuusisto J.S.
- Juhana Laurinharju Jonni Virtema

What is distributed computing?

Centralized vs. distributed

- Theory of *centralized* computing:
 - "what can be computed efficiently with my laptop?"
 - input & output: encoded as a string
 - model of computing: Turing machines
- Theory of *distributed* computing:
 - ???

Distributed computing

- Can mean lots of different things
 - causes lots of confusion
- I'll explain two commonly used interpretations
 - these are just "two extremes"
 - there is a whole spectrum of variants between them

Big data perspective

"*Too large* for my laptop to solve, I'll have to resort to Amazon cloud"

Network algorithms

"How to coordinate data transmissions in a large network *without centralized control*?"

Big data perspective

Network algorithms





Big data perspective

- Focus:
 computation
- Distributed perspective helps us

Network algorithms

- Focus: communication
- Distributed perspective additional challenge

Big data perspective

• Fully centralized control

Network algorithms

 No centralized control

- Global perspective
- Input & output in one place

- Local perspective
- Input & output distributed

Big data perspective

 I know everything about input

I need to know
 everything about solution

Network algorithms

- Each node knows its own part of input
 - e.g. local constraints
- Each node needs its own part of solution
 - e.g. when to switch on?

Big data perspective

- Explicit input
 - encoded as a string, stored on my laptop
- Well-known network structure
 - tightly connected cluster computer

Network algorithms

- Implicit input
 - input graph = network structure
- Unknown
 network structure
 - e.g. entire global Internet right know

Big data perspective

Can we divide problem in small independent tasks that can be solved in parallel?

Network algorithms

If each node is only aware of its **local neighborhood**, can we nevertheless find a **globally consistent solution**?

Big data perspective



Network algorithms



- Initial knowledge:
 - local input, number of neighbors
- Communication round:
 - send message to each neighbor
 - receive message from each neighbor
 - update state
 - possibly: announce local output and stop



- Each node labeled with a "unique identifier"
 - constant k such that if we have a graph with n nodes, unique identifiers are distinct values from { 1, 2, ..., n^k }



Equivalent:

- "running time"
- number of synchronous
 communication rounds
- how far do we need to look in the graph



Fast algorithm ↔ highly "localized" solution

- The usual computer science perspective:
 - what is the worst-case running time?
 - asymptotically, as a function of n
- Two-player game:
 - player A chooses the algorithm
 - player B then chooses the graph, local inputs, unique identifiers

- Everything is computable in O(n) rounds!
 - assuming a connected graph
 - gather everything, solve locally by brute force
 - exploits: large messages, unlimited local computation
- Interesting question: what can be done in o(n) rounds?

- Example: graph coloring with k colors
 - local input: nothing
 - local output: what is my own color
 - constraint: adjacent nodes have different colors

- Example: graph coloring with k colors
- Graph family: *path* with *n* nodes
 - *k* = 2: **O**(*n*) rounds
 - *k* = 3: **O**(log* *n*) rounds
 - *k* = 100: **O(log*** *n*) rounds

- Example: graph coloring with k colors
- Graph family: 2D grid with n × n nodes
 - *k* = 2: **O**(*n*) rounds
 - *k* = 3: **O**(*n*) rounds
 - *k* = 4: **O(log*** *n*) rounds
 - *k* = 100: **O(log*** *n*) rounds

- Example: weak 2-coloring
 - label nodes with {0, 1}
 - each node has a neighbor with a different label
- Graph family: regular graphs
 - 4-regular graphs: O(log* n) rounds
 - 5-regular graphs: O(1) rounds

- Why do we keep seeing "Θ(log* n)"?
- All of these are algorithms that exploit *numerical values of unique identifiers*
 - more precisely, it is Θ(log* s), where s = size of the identifier space
 - we just assumed that s = poly(n)

• What if we don't have unique identifiers?

Weak models of distributed computing

- Initial knowledge:
 - local input, number of neighbors
- Communication round:
 - send message to each neighbor
 - receive message from each neighbor
 - update state
 - possibly: announce local output and stop



- Key difference: nodes are identical
 - no unique identifiers
 - "anonymous networks"

- How to refer to your neighbors?
- Port-numbering model:
 - node of degree d can refer to its neighbors with numbers 1, 2, ..., d
 - "this is the message that I got from neighbor x"
 - "I want to send this message to neighbor *x*"

- How to refer to your neighbors?
- Set-broadcast model:
 - no way to refer to specific neighbors
 - "this is the set of messages that I got from my neighbors in this round"
 - "I want to broadcast this message to all neighbors"

Weak models: computability

- Many problems cannot be solved at all
- Key challenges:
 - breaking symmetry
 - detecting cycles

Breaking symmetry

- Example: graph coloring
- Input graph: o---o
- Impossible to solve!

Breaking symmetry

- Input graph: o—o
- Proof:
 - same state before round t
 - same outgoing messages
 - same incoming messages
 - same state after round *t*

Detecting cycles

 Not possible to tell the difference between these graphs



Detecting cycles

- Not possible to tell the difference between these graphs
 - **Proof:** covering maps preserve everything

- Lots of different models of distributed computing
 - "VV", "MV", "SV", "VB", "MB", "SB" ...
- Key questions about each model:
 - which problems can be solved at all?
 - which problems can be solved *in constant time*?

Logical characterizations

Weak models & modal logic

- Natural 1:1 correspondence between:
 - constant-time distributed algorithms set—broadcast model
 - formulas in basic modal logic
- Both equally expressive: can "solve" the same set of graph problems

Modal logic & computing

- Textbook approach:
 - possible world ≈ possible state of the system
 - accessibility relation ≈ state transition
- Our perspective:
 - possible world ≈ computer
 - accessibility relation ≈ communication link

Modal logic		Distributed algorithms
Kripke model $K = (W, (R_{\alpha})_{\alpha \in I}, \tau)$	{	input graph $G = (V, E)$ port numbering p
states W relations $R_{\alpha}, \ \alpha \in I$		nodes V edges E and port numbering p
valuation τ proposition symbols q_1, q_2, \ldots	}	node degrees (initial state)
formula φ formula φ is true in state v modal depth of φ		algorithm \mathcal{A} algorithm \mathcal{A} outputs 1 in node v running time of \mathcal{A}

PODC 2012 (Symposium on Principles of Distributed Computing)

Technology transfer

Using tools from logic to prove results on distributed computing e.g. bisimulation





What has happened since 2010?

Beyond constant time

- Easy: running time ≈ operator depth
- Much more challenging to capture: non-constant running time

Beyond constant time

- Promising approach: *fixed-point logic*
 - e.g. modal µ-calculus
 - Antti Kuusisto (CSL 2013)
 - Fabian Reiter (ICALP 2017)

Nondeterminism & alternation

- Stronger models of distributed computing
 - cf. nondeterministic & alternating Turing machines
 - cf. class NP & polynomial hierarchy
- Logical characterizations:
 - "alternating local distributed automata"
 ≈ monadic second-order logic
 - Fabian Reiter (LICS 2015)

Nondeterminism & alternation

- Active research topic: distributed decision
 - yes-instance: all nodes say "yes"
 - no-instance: at least one node says "no"
- E.g.: O(log n) bits per node per quantifier
 - Göös, S. (PODC 2011)
 - Feuilloley, Fraigniaud, Hirvonen (ICALP 2016)

What is happening right now?

- Centralized computing:
 - time hierarchy theorem
 - more time \rightarrow can solve more problems
- Distributed computing:
 - gap results
 - $o(\log n)$ rounds \approx as good as $O(\log^* n)$ rounds

- Key idea that has enabled lots of progress: identify the right family of problems
 - do not try to prove something about "all graph problems"
 - focus on "LCL problems" (locally checkable labeling)
 - distributed analogue of class NP: solutions are easy to verify, but may be hard to find

- Lots of progress:
 - Brandt et al. (STOC 2016)
 - Chang et al. (FOCS 2016)
 - Ghaffari & Su (SODA 2017)
 - Brandt et al. (PODC 2017)
 - Chang & Pettie (FOCS 2017)
 - Balliu et al. (STOC 2018) ...

- One of the current obstacles: we seem to be still *lacking the right definitions*
 - example: LCLs work well for graphs of maximum degree O(1), but how to generalize beyond that?
- Could we try to replace the current algorithmic or graph-theoretic definitions with *logical characterizations*?

Thanks! Happy Birthday!

Helsinki · Finland 20-24 August 2018 ALGO2018

